

Rubik's Cube Solver using Thistlewaiste's ES Strategy
"An Evolutionary Approach for Solving"
"the Rubik-Cube Incorporating Exact Methods"
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Abstract

The research paper "An Evolutionary Approach for Solving the Rubik-Cube Incorporating Exact Methods" by Nail El-Sourani, Sascha Hauke, and Markus Borschbach, University of Applied Sciences, Germany applies group theory and evolutionary strategy to solve Rubik's Cube. Though previously too there have been methods to solve the Rubik's Cube, like Thistlewaiste's and Kociemba's and Rokicki's The nobility with their approach is that it doesnot require terabytes of lookup tables unlike the former algorithms. However, the integrity and success of their method is still needs to tested and verified.

1 **1. Introduction**

2 Rubik's Cube since introduced in 70's has been the most intriguing puz-
3 zles in the history of mankind. It is a challenging task. The size of the
4 solution space because possible number of configurations of the Rubik's cube
5 and an attempt to optimize the solution, i.e. lowest possible number of moves
6 and lowest calculation complexity makes it a very interesting optimization
7 problem. The least possible number of moves to solve the Rubik's Cube,
8 also known as the God's number is however yet unknown. All the algorithms
9 so far have focused on decreasing the upper bound. All the approaches so
10 far are strictly exact methods and require terabytes of pre-calculated lookup

11 tables, reflected by current lowest upper bound of 22 moves(ROKICKI'S
12 ALGORITHM).

13 Evolutionary or Genetic Algorithms have been applied in a large number
14 of problems, like the Traveling Salesman Problem, and sometime deliver
15 better superior solutions than the classical algorithms. This suggests the idea
16 of applying it to solve the Rubik's Cube. All relevant methods so far involve
17 partitioning the solution space into mathematical groups. Thistlewaiste's
18 uses 4, while Kociemba's and Rokicki's uses 2 subgroups. This makes their
19 approach precursor for developing Evolutionary Algorithms; interesting issue
20 is to do it without look-up tables.

21 2. Thistlewaiste's Algorithm

22 Among of the one of primary exact methods, it was chosen to work fur-
23 ther on developing an Evolutionary Algorithm for solving the Rubik's Cube.
24 TWA divides the problem into four subproblems using the four nested groups:
25 $G_0 = \langle F, R, U, B, L, D \rangle$, $G_1 = \langle F, U, B, D, R^2, L^2 \rangle$, $G_2 = \langle U, D, R^2, L^2, F^2, B^2 \rangle$,
26 $G_3 = \langle F^2, R^2, U^2, B^2, L^2, D^2 \rangle$, $G_4 = I$ i.e. the Solved State. The functional prin-
27 ciple is to put the cube into a state such that it can thence be solved only
28 from moves in the sequences generated from $G_{(i+1)}$ group. The state is
29 however achieved by using moves from the $G_{(i)}$ group. Every stage is simply
30 a lookup table showing a transition sequence for each element in the current
31 coset space G_{i+1}/G_i to the next one ($i=i+1$). These coset spaces are re-
32 finements of the earlier solution, limiting the possible configurations of the
33 Rubik's cube in each state.

34 EXCERPT TAKEN FROM THE RESEARCH PAPER An Evolutionary
35 Approach for Solving the Rubiks Cube Incorporating Exact Methods: AL-
36 GORITHM

37 The exact orders for each group are calculated as follows: $G_0, |G_0| = 4.33 * 10^{19}$
38 represents the order of the Cube Group.

39 G_1 : The first coset space G_1/G_0 contains all Cube states, where the edge
40 orientation does not matter. This is due to the impossibility of flipping
41 edge cubies when only using moves from G_1 . As there are 2^{11} possible edge
42 orientations, $|G_1/G_0| = 2^{11} = 2048$

43 The order of $|G_1|$ is $|G_1||G_0||G_1/G_0| = 2.11 * 10^{16}$.

44 (2) G_2 Using only moves from G_2 , no corner orientations can be altered (elim-
45 inating 3^7 states). Additionally, no edge cubies can be transported to or from
46 the middle layer (eliminating $12!/(8!*4!)$ states). The coset space G_2/G_1 thus

47 depicts a reduced puzzle of the order $|G_2/G_1| = 3^7 * 12!/(8! * 4!) = 1082565$
 48 and $|G_2||G_1|/|G_2/G_1| = 1.95 * 10^{10}$
 49 (4) G_3 : Once in the coset space G_3/G_2 , the Cube can be solved by only
 50 using moves from G_3 , here the edge cubies in the L, R layers can not trans-
 51 fer to another layer (eliminating $8!/(4!*4!)*2$ states) and corners are put
 52 into their correct orbits, eliminating $8!(4!*4!)*3$ states). Thus, $|G_3/G_2| =$
 53 $(8!/(4! * 4!)) * 2 * 2 * 3 = 29400$ and $|G_3||G_2|/|G_3/G_2| = 6.63 * 10^5$.
 54 G_4 as G_4 represents the solved state - obviously $|G_4| = 1$ which means there
 55 exist a mere $|G_3|$ possible states for which a solution needs to be calculated to
 56 transfer from G_4/G_3 to solved state. Most essential to TWA are the groups
 57 G_1, G_2, G_3 as G_0 simply describing the Cube Group G_c and G_4 the solved
 58 state. To further exemplify how the coset spaces simplify the Rubiks Cube
 59 puzzle the following may prove helpful. When looking at the constraints in-
 60 duced by $G_2/G_1/G_0$ carefully (combining the constraints induced by G_2/G_1
 61 and G_1/G_2) it is essentially a Rubiks Cube with only 3 colors - counting
 62 two opposing colors as one. This representation can be reached for each
 63 distinct coset space by examining and applying its effect to the complete
 64 Rubiks Cube puzzle. While solving the Rubiks Cube in a divide and conquer
 65 manner, breaking it down into smaller problems (by generating groups and
 66 coset spaces) is effective, there exists one major flaw. Final results obtained
 67 by concatenating shortest subgroup solution do not necessarily lead to the
 68 shortest solution, globally.

69 **3. The Thistlethwaite ES - An Evolution Strategy Based on the** 70 **Thistlethwaites Algorithm**

71 In the classic TWA the order of each subproblem get reduced from stage
 72 to stage. This algorithm present a 4-phase ES. Each phase here has a fitness
 73 function.

74 A scrambled Cube is duplicated t times and the main loop is entered with
 75 a fitness function. Mutation sequences are generated using the group G_0
 76 started using a fitness function $phase_0$. As soon as Cubes which solve $phase_0$
 77 have been evolved, the phase transition begins. During phase transition, from
 78 those $phase_0$ -solving Cubes, a random Cube is chosen and duplicated. This
 79 is repeated t times and yields in the first population after the phase transition.
 80 Now the phase-counter is increased by one, and the main ES loop is entered
 81 again. This process is repeated until $phase_4$ is solved (i.e. $phase_5$ is reached),
 82 presenting a solution sequence to the originally scrambled Cube. In order to

83 avoid the TWES getting stuck in local optima an upper bound for calculated
84 generations is introduced. As soon as this upper bound is reached, the chain
85 is terminated,

86 Fitness Function translating the TWA into an appropriate Fitness Function
87 for an Evolutionary Algorithm essentially forces the design of four distinct
88 sub-functions. As each subgroup of G_0 has different constraints, custom
89 methods to satisfy these constraints are proposed.

90 EXCERPT FROM THE RESEARCH PAPER: An Evolutionary Approach
91 for Solving the Rubiks Cube Incorporating Exact Methods: ALGORITHM

92 G_0 to G_1 To reach G_1 from any scrambled Cube, we have to orient all
93 edge pieces right while ignoring their position. The fitness function for this
94 phase simply increases the variable $phase_0$ by 2 for each wrong oriented edge.
95 Furthermore, we add the number of moves that have already been applied to
96 the particular individual in order to promote shorter solutions. Finally, we
97 adjust the weight between w (number of wrong oriented edges) and c (number
98 of moves applied to current Cube individual). This will be done similarly in
99 all subsequent phases.

100

101 $phase_0 = 5 * (2w) + c$ With a total of 12 edges which can all have the
102 wrong orientation this gives $\max 2w = 24$. The Cube has been successfully
103 put into G_1 when $phase_0 = c$. Reaching G_1 is fairly easy to accomplish, thus
104 making the weight-factor 5 a good choice.

105

106 G_1 to G_2 In order to fulfill G_2 the 8 corners have to be oriented correctly.
107 Edges that belong in the middle layer get transferred there. Tests with the
108 Thistlethwaite ES showed it somewhat problematic to do this in one step.
109 Oftentimes, the algorithm would get stuck in local optima. To solve this, the
110 process of transferring a Cube from G_1 to G_2 has been divided into two parts.
111 First, edges that belong into the middle layer are transferred there. Second,
112 the corners are oriented the right way. The first part is fairly easy and the
113 fitness function is similar to that from $phase_0$ except for w (number of wrong
114 positioned edges), i.e. edges that should be in the middle layer but are not.
115 $phase_1 = 5(2w) + c$. In the second part, for each wrong positioned corner, 4
116 penalty points are assigned as they are more complex to correct than edges.
117 Obviously, in order to put the Cube from G_1 to G_2 both phases described
118 here have to be fulfilled, which yields: $phase_2 = 10(4v) + phase_1$ where v
119 represents the number of wrong oriented corners. The weighing factor is in-
120 creased from 5 to 10 to promote a successful transformation into G_2 over a

121 short sequence of moves.

122

123 G_2 to G_3 We now have to put the remaining 8 edges in their correct orbit.
124 The same is done for the 8 corners which also need to be aligned the right
125 way. Thus, the colors of two adjacent corners in one circuit have to match
126 on two faces. In G_3 the Cube will only have opposite colors on each face.
127 Let x (number of wrong colored facelets) and y (number of wrong aligned
128 corners), then $phase_3 = 5(x + 2y) + c$.

129 An Evolutionary Approach for Solving the Rubiks Cube G_3 to G_4 (*solved*)
130 The Cube can now be solved by only using half-turns. For the fitness function
131 we simply count wrong colored facelets. Let z be the number of wrong colored
132 facelets, then $phase_4 = 5z + c$.

133 To summarize, 5 different fitness functions are needed for the Thistlethwaite
134 ES. $phase_i$ is solved if $phase_i = c$, $i=0, \dots, 4$ and with the properties of nested
135 groups we can conclude, given the above, a solved Cube implies: $phase_i = c$.
136 Fulfilling the above equation satisfies the constraints induced by the groups
137 G_0, \dots, G_4 , with the final fitness value c describing the final solution sequence
138 length. The maximum sequence length (s) needed to transform the Cube
139 from one subgroup to another is given by Thistlethwaite. Those lengths are
140 7,13,15,17 (the sum of which is 52, hence 52 Move Strategy).

141 4. Conclusion

142 Verification of the claims of the testbenchs and results given in the re-
143 search paper is still under process. No result can therefore be quoted hence-
144 far. We expect however, the algorithm delivers as promised. Work is cur-
145 rently under progress. Code would be uploaded on github, and link shared.

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