



Simulation of Usage-Based Language Acquisition in Ernest

Mentor

Dr. Amitabh Mukherjee

Project Proposal by

Diksha Gupta



Theories of Language Acquisition

- Generativist Approach by Noam Chomsky
- Empiricist Approach by Bates, Powells, MacWhinney, Tomasello
 - Usage-based Grammar by Tomasello



Generative Grammar (Chomsky)

- Presence of innate universal grammar which imposes constraints on infant's hypothesis space.
- Which is to say, that grammar is not ontogenetically learnt (Poverty of Stimulus Argument)

Phonemes, words associated with to a specific language are contextually learnt and mapped onto an innate grammar.



Usage-based Grammar (Tomasello)

- Language acquisition as context-driven statistical abstractions
- Grammatical rules partly syntactic but also semantic: stated in terms of their pattern of use and communicative function
- Innate cognitive abilities for language acquisition are not language specific.
 Instead they are:
 - · intention inference
 - pattern finding and
 - predisposition towards social communication



My Proposal



Simulation of grounded, usage-based grammar acquisition in an artificial agent: Ernest



Ernest

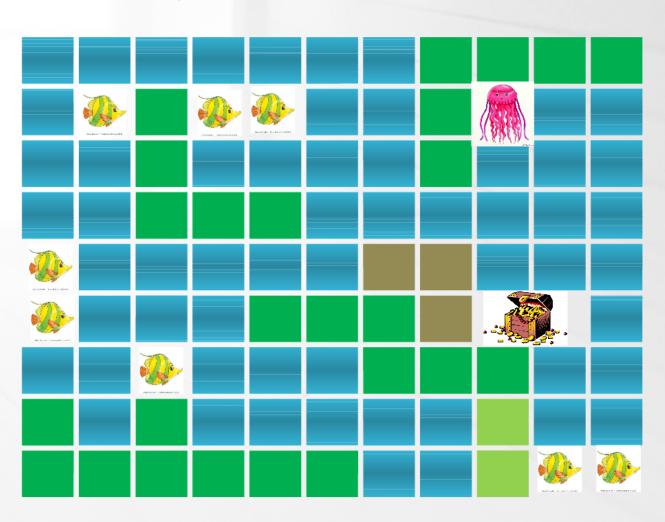
Artificial agent simulated by Georgeon, Ritter

It implements emergent learning phenomena as theorized in natural organisms

It has intrinsic motivations and is capable of simulating course of action through inhibition.



Aquarium: Tentative Environment for Interaction



Jellyfish: Ernest

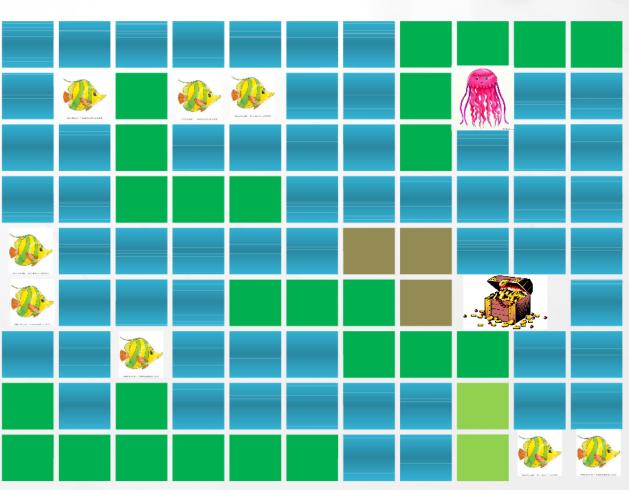
Objects (nouns) in the grid:

- Fish (food)
- Algae (food)
- Treasure chest
- Rocks
- Plants

Perceptuo-motor Space:

- · move one block forward
- bump
- turn left/right
- eat
- sense (touch) any adjacent block





- Perceptuo-motor space:
 - · move one block forward
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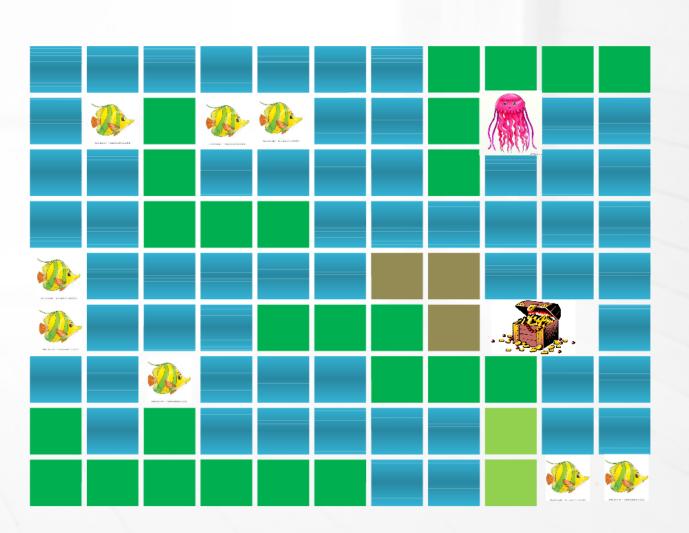
Possible interactions (verbs):

- Hit (Rocks, Plants, Treasure Chest)
- Eat (Fish, Algae)
- See (Treasure, Rock, Plants)
- Smell (Food: fish, algae)
- Turn, Move (in water)

Two phenomenons:

- Lexicon Acquisition
- Syntax Acquisition





- When Ernest will interact with the environment, it will read sentences narrating the action it is performing.
- Through bayesian cross-model association it will ground the words with the concepts.
- Also, it will observe the regularities in the nature of its action and linguistic utterances and consequently, learn syntax.

Current Status

- Planning the environment and possible interactions
- Building the corpus of training sentences
- Studying algorithms for cross-modal associative learning. (Hidden Markov Models)



References

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Thank You!

